Context

Reconfigurable Broadcast Networks (RBN) are a model for large groups of identical agents communicating via unreliable broadcast. A pushdown RBN (PRBN) is simply one where each agent is modelled by a pushdown transition system.

A PRBN is described by a tuple $(Q, M, \Gamma, \Delta, q_0)$ where Q is a finite set of states, M a finite alphabet of messages, Γ a finite stack alphabet with a special letter \perp , q_0 an initial state, and

 $\Delta \subseteq Q \times \{\mathbf{br}(m), \mathbf{rec}(m) \mid m \in M\} \times \{push(\gamma), pop(\gamma), nop \mid \gamma \in \Gamma\} \times Q$

a transition function.

A run starts with an arbitrarily large set of agents, all in state q_0 . A step consists of one agent executing a transition with a broadcast $\mathbf{br}(m)$, and an arbitrary subset of other agents executing a transition with a matching reception $\mathbf{rec}(m)$.

Formally, a local configuration is a pair $(q, \sigma) \in Q \times \Gamma^*$. A local step $(q, \sigma) \xrightarrow{op_1} (q', \sigma')$ is defined when there exists a transition (q, op_1, op_2, q') such that either:

- $op_2 = push(\gamma)$ and $\sigma' = \gamma \sigma$
- $op_2 = pop(\gamma)$ and $\sigma = \gamma \sigma'$
- $op_2 = nop$ and $\sigma' = \sigma$

A configuration is a function from a finite non-empty set of agents \mathbb{A} to the set of local configurations $C : \mathbb{A} \to Q \times \Gamma^*$. An initial configuration is such that $C(a) = (q_0, \bot)$ for all $a \in \mathbb{A}$. A step $C \to C'$ is defined when there exists an agent $a_{\mathbf{br}}$ such that there is a local step $C(a_{\mathbf{br}}) \xrightarrow{\mathbf{br}(m)} C'(a_{\mathbf{br}})$ and for all $a \neq a_{\mathbf{br}}$, either

- there is a local step $C(a) \xrightarrow{\operatorname{\mathbf{rec}}(m)} C'(a)$, or
- C(a) = C'(a)

A run is a sequence of consecutive steps, it is initial if it starts in an initial configuration.

Classical problems on such models ask whether a given set of configurations is reachable. A particular case of interest is the reachability of a configuration where all agents are in a given subset of states $S \subseteq Q$. This problem is called Target.

The open problem is to find tight complexity bounds on the Target problem for PRBN. The problem on fnite-state RBN is known to be solvable in polynomial time. An easy reduction from Horn satisfiability shows PTIMEcompleteness. On the other hand, one can show that the problem for PRBN is in NP: to witness Target, one can guess a set of messages $M' \subseteq M$ of messages used, and two orders on this set, an order of appearance \leq_a and one of disappearance \leq_d .

It suffices to check that for all $m \in M'$ there exists a run $(q_0, \bot) \xrightarrow{*} (q, \sigma) \xrightarrow{*} (q_f, \sigma_f)$ only receiving messages smaller than m for \leq_a on the first part and messages from M' on the second part, as well as a run $(q_0, \bot) \xrightarrow{*} (q', \sigma') \xrightarrow{*} (q_f, \sigma_f)$ only receiving messages from M' on the first part and from $\{m' \in M' \mid m' \leq_d m\}$ on the second one.

This can be checked in polynomial time.

Credits and related work

RBN were introduced (with finite-state systems) in [2], and the precise complexity of the main problems was analysed more finely in [3]. Pushdown RBN were introduced in [1], with in particular a proof that the coverability problem (whether there is a reachable configuration with at least one agent in a given state q_f) is decidable in PTIME for this model.

References

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